





Always in use

EAS®-HT torque limiters for heavy load applications prolong the availability of your production systems.

They increase your profit, prevent damage caused by overload damages and save costs.

EAS®-HT torque limiters

the reliable, non-destructive overload protection

- Disengaging
- Steplessly adjustable
- Precise
- Compact
- Robust



Tested safety

For more than 40 years, we have been dimensioning, developing and manufacturing torque limiters for heavy load applications.

You can rely on the tested reliability and safety of our heavy load clutch.

Experts, not experiments

as safety does not allow for compromises





EAS®-HT short bearing-supported hub



Torque: 1.4 bis 42 kNm

Sizes 7 to 10 Type 4050._0400

- Direct attachment of the drive element on the bearing-supported, output-side clutch flange.
- The bearing is able to absorb high additional forces in axial and radial directions.

Page 6

EAS®-HT lastic



Torque: 1.4 bis 42 kNm

Sizes 7 to 10 Type 4053._0400

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

Page 8

EAS®-HT flange design



Torque: 7.5 to 440 kNm

Sizes 0 to 6 Type 4060.71400

- Compact, ready-to-install module
- Can easily be integrated into the drive line

Page 10

EAS®-HT Toothed coupling



Torque: 7.5 to 440 kNm

Sizes 0 to 6 Type 4061.71400

- Double shaft design
- Toothed coupling with crowned teeth cutting
- Robust and temperature-resistant
- High misalignment compensation capability

Page 12

EAS®-HT backlash-free



Torque: 7.5 to 140 kNm

Sizes 0 to 4 Type 4062.71400

- Double shaft design with a torsionally rigid, backlash-free disk pack coupling
- High torsional rigidity
- Backlash-free torque transmission
- Maintenance-free

Page 14

EAS®-HT lastic bolt



Torque: 40 to 260 kNm

Sizes 3 to 5 Type 4063.70400

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

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EAS®-HT Options

Customer-specific designs Low temperature design Alternative shaft connections ATEX

Page 18

EAS®-elements

- Standard
- Reinforced



- Torque limiting or force limiting elements
- Installation into two flanges located towards one another
- Integration into existing constructions possible

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Technical Explanations

General
Pre-selection
Misalignment compensation capability

Page 23

Additional branch-optimised EAS® torque limiters

High-speed clutches EAS®-HSE



Torque: 100 to 8.400 Nm

Sizes 02 to 0 Type 404_ . _04_ _ Reliable overload protection at high speeds

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-HSC/ EAS®-HSE.

Extruder clutches EAS®-dutytorque



Torque: 70 to 17.000 Nm

Sizes 2 to 9 Type 4043. _1400 Protect extruder screws

from expensive damage caused by overload

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-dutytorque.

Rustproof design



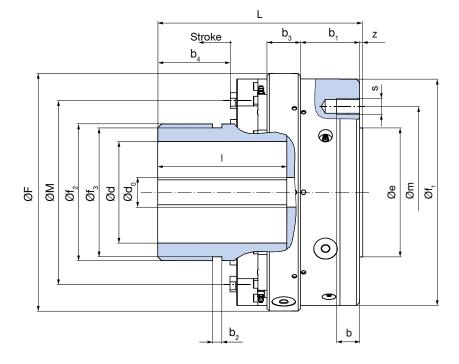


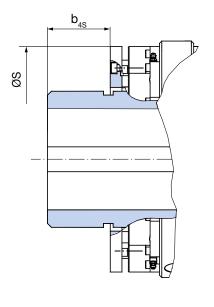
Corrosion-protected torque limiters for environmental and waste water technology



Short bearing-supported hub

Type 4050._0400 Sizes 7 to 10









Optionally available with switching disk

Order Number

without switching disk 0
with switching disk 1

0 Bores 1) Sizes Torque adjustment value Torque range 1) **Bore** 4 5 low $Ø d^{H7}$ $Ød_0$ [kNm] medium to 6 7 10 high Keyway acc. DIN 6885/1 very high - P9

Example: Order Number 8 / 4050.60400 / 90 / 35 / 8 / 0

1) Position of the keyway to the tapped hole "s" in the thrust piece is not defined. Defined position available on request.

| Technical Dat | to. | | | | Siz | es | |
|--------------------------------------|---|---------------|--------|------------|------------|------------|-------------|
| recrimical Da | ıd | | | 7 | 8 | 9 | 10 |
| | Type 4050. 4 0400 M _G | | | 1.4 - 2.8 | 1.7 - 3.4 | 4 - 8 | 5.2 - 10.4 |
| | Number of | EAS®-elements | | 2 | 2 | 4 | 2 |
| Type 4050. 5 0400 | | M_{G} | [kNm] | 2.1 - 4.2 | 3.5 - 7 | 6 - 12 | 10.5 - 21 |
| Limit torques Number of for overload | | EAS®-elements | | 3 | 4 | 6 | 4 |
| ior overioau | Type 4050. 6 0400 | $M_{\rm G}$ | [kNm] | 2.8 - 5.6 | 5.2 - 10.4 | 8 - 16 | 15.7 - 31.4 |
| | Number of | EAS®-elements | | 4 | 6 | 8 | 6 |
| | Type 4050. 7 0400 | M_{G} | [kNm] | 4.25 - 8.5 | 7 - 14 | 14 - 28 ¹) | 21 - 42 |
| | Number of | EAS®-el | ements | 6 | 8 | 8 | 8 |
| Sizes EAS®-elem | sizes EAS®-elements | | | 0 | 0 | 0 | 1 |
| Maximum speed | Maximum speed | | [rpm] | 3000 | 2800 | 2500 | 2200 |
| Bolt stroke on ov | Bolt stroke on overload | | [mm] | 6 | 6 | 8 | 8 |

¹⁾ Equals Type 4050.71400

| Max. permitted forces on the fl | lange c | on- | | Siz | zes | |
|---------------------------------|---------|-----|----|-----|-----|--|
| nection | | 7 | 8 | 9 | 10 | |
| Radial forces | [kN] | 15 | 20 | 30 | 40 | |
| Axial forces Type 40500400 | 10 | 15 | 20 | 30 | | |

| Mass momen | its of inertia and w | eight | s | Size | | | | | | |
|----------------------------|----------------------|-------|--------|--------------|--------------|--------------|--------------|--|--|--|
| (* with switching disk) | | | | 7 | 8 | 9 | 10 | | | |
| EAS®-hub side | Type 40500400 | J | [kgm²] | 0.18 / 024* | 0.38 / 0,45* | 1.05 / 0,90* | 2.37 / 3,10* | | | |
| Flange side | Type 40500400 | J | [kgm²] | 0.17 / 0,22* | 0.38 / 0,45* | 1.3 / 1,03* | 2.65 / 3,32* | | | |
| Weight at d _{max} | Type 40500400 | | [kg] | 50 / 54* | 76 / 81* | 126 / 132* | 247 / 260* | | | |

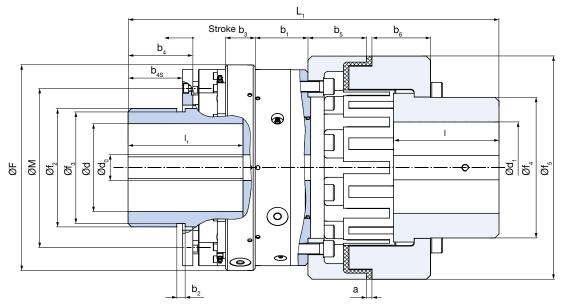
| Roros [mm] | | | Siz | zes | |
|---------------|--------------------|-------------------|-------------------|-------------------|-------------------|
| Bores [mm] | | 7 | 8 | 9 | 10 |
| EAS®-hub side | d _{max} | 100 ^{H7} | 130 ^{H7} | 160 ^{H7} | 200 ^{H7} |
| Flange side | d _{o max} | 30 | 38 | 48 | 58 |

| Dimensions | | Siz | es | |
|-------------------|-------|-------|-------|--------|
| [mm] | 7 | 8 | 9 | 10 |
| b | 25 | 30 | 40 | 35 |
| b ₁ | 66 | 78 | 104 | 115 |
| b_2 | 12.5 | 12.5 | 15 | 15 |
| b ₃ | 44 | 44 | 46 | 56 |
| b ₄ | 63.8 | 93.8 | 134.8 | 148.3 |
| b _{4S} | 50.8 | 80.8 | 121.8 | 130.3 |
| e _{h7} | 147 | 165 | 242 | 276 |
| F | 265 | 304 | 350 | 450 |
| f ₁ | 250.5 | 289.5 | 334.5 | 432.5 |
| $\mathbf{f_2}$ | 135 | 175 | 220.5 | 280 |
| f ₃ | 125 | 165 | 210 | 265 |
| L | 228 | 270 | 340 | 392 |
| I | 140 | 170 | 210 | 250 |
| М | 115 | 235 | 280 | 360 |
| m | 190 | 220 | 285 | 325 |
| S | 8xM16 | 8xM20 | 8xM24 | 12xM24 |
| S | 250 | 290 | 335 | 435 |
| z | 4 | 4 | 5 | 6 |

We reserve the right to make dimensional and constructional alterations.



Type 4053._0400
Sizes 7 to 10







Optionally available with switching disk (Dimensioning see page 6)

Order Number

without switching disk with switching disk 1

| | / 4 | 0 | 5 | 3 | · | 0 | 4 | 0 | 0 | / | _ | / | | / | _ | / | _ | / | |
|------------------------|--|---|---|---|------------------|---|---|---|---|---|---|-------|--------------------------------------|---|--|---|---|---------------------------------|------|
| | | | | | \triangle | | | | | | | | \triangle | | | | | | |
| Sizes 7 to 10 | Torque low mediu high very h | | | | 4 5 6 7 | | | | | | Bore Ø d ^{H7} Keywa | y acc | Bore Ø d _o c. DIN 6 | | Bore Ø d ₁ ^{H7} /1 - P9 | | | adjust value [kNm] | ment |

Example: Order Number 8 / 4053.60400 / 90 / 35 /115 / 8 / 0

| Ta abusia al alat | _ | | | | | Siz | es | |
|---|------------------------------|----------------------------|------------------------------------|-----------|------------|-----------|-----------------------|------------|
| Technical dat | а | | | | 7 | 8 | 9 | 10 |
| | Type 4053.4 | 4 0400 | $M_{\scriptscriptstyle G}$ | [kNm] | 1.4 - 2.8 | 1.7 - 3.4 | 4 - 8 | 5.2 - 10.4 |
| | Number of | | | | 2 | 2 | 4 | 2 |
| | | | M _G [kNm | | 2.1 - 4.2 | 3.5 - 7 | 6 - 12 | 10.5 - 21 |
| Limit torques for overload Number of EA | | | EAS®-e | lements | 3 | 4 | 6 | 4 |
| Type 4053. 6 0400 | | $M_{\scriptscriptstyle G}$ | [kNm] | 2.8 - 5.6 | 5.2 - 10.4 | 8 - 16 | 15.7 - 31.4 | |
| Number of | | | EAS®-elements | | 4 | 6 | 8 | 6 |
| | Type 4053.7 | 7 0400 | $M_{\rm G}$ | [kNm] | 4.25 - 8.5 | 7 - 14 | 14 - 28 ²⁾ | 21 - 42 |
| | N | umber of | EAS®-e | lements | 6 | 8 | 8 | 8 |
| Sizes EAS®-elem | ents | | | | 0 | 0 | 0 | 1 |
| Maximum speed | | | n _{max} | [rpm] | 2250 | 2000 | 1500 | 1400 |
| Bolt stroke on ov | verload | | | [mm] | 6 | 6 | 8 | 8 |
| Permitted axial | | axial | $\Delta K_{\scriptscriptstyle{a}}$ | [mm] | ±2.5 | ±2.5 | ±2.5 | ±2.5 |
| Flexible misalign- radial | | ΔK_r | [mm] | 0.3 | 0.3 | 0.3 | 0.3 | |
| onar oouping | ments 1) angular | | ΔK_{w} | [mm] | 0.3 | 0.3 | 0.3 | 0.3 |
| Nominal and ma | Nominal and maximum torques, | | T _{KN} [kNm] | | 5.8 | 9.9 | 20.5 | 28 |
| flexible coupling | | | T _{K max} | [kNm] | 8.3 | 14.5 | 27 | 66 |

The values refer to 1500 rpm.
 Entspricht Type 4053.71400

| Mass momen | ts of inertia and w | eight | S | Sizes | | | | | | |
|-------------------------------|---------------------|-------|---------------------|--------------|--------------|--------------|---------------|--|--|--|
| (* with switching disk) | | | | 7 | 8 | 9 | 10 | | | |
| Mass moments of EAS®-hub side | | J | [kgm²] | 0.18 / 0,24* | 0.38 / 0,45* | 1.05 / 0,90* | 2.37 / 3,10* | | | |
| inertia | Flexible side | J | [kgm ²] | 0.57 / 0,62* | 1.62 / 1,69* | 5.0 / 4,8* | 10.7 / 11,28* | | | |
| Weight at d _{max} | | | [kg] | 88 / 92* | 154 / 158* | 276 / 281* | 478 / 491* | | | |

| Paras [mm] | | | Sizes | | | | | | |
|---------------|--------------------|-------------------|-------------------|-------------------|-------------------|--|--|--|--|
| Bores [mm] | | 7 | 8 | 9 | 10 | | | | |
| EAS®-hub side | d _{max} | 100 ^{H7} | 130 ^{H7} | 160 ^{H7} | 200 ^{H7} | | | | |
| Flange side | d _{0 max} | 30 | 38 | 48 | 58 | | | | |
| Flexible side | d _{1 max} | 115 ^{H7} | 135 ^{H7} | 180 ^{H7} | 200 ^{H7} | | | | |

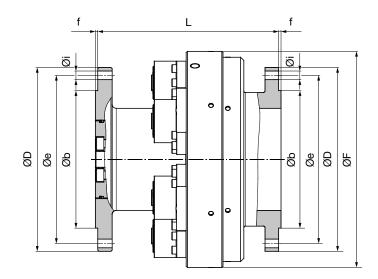
| Dimensions | | Siz | zes | |
|-----------------------|-------|-------|-------|-------|
| [mm] | 7 | 8 | 9 | 10 |
| а | 5.5 | 8 | 8 | 8 |
| b ₁ | 66 | 78 | 104 | 115 |
| b_2 | 12.5 | 12.5 | 15 | 15 |
| b ₃ | 44 | 44 | 46 | 56 |
| b ₄ | 63.8 | 93.8 | 134.8 | 148.3 |
| b _{4S} | 50.8 | 80.8 | 121.8 | 130.3 |
| b ₅ | 76 | 86.5 | 102 | 108 |
| b ₆ | 76 | 86.5 | 102 | 108 |
| F | 265 | 304 | 350 | 450 |
| f ₂ | 135 | 175 | 220.5 | 280 |
| f ₃ | 125 | 165 | 210 | 265 |
| f ₄ | 164 | 208 | 275 | 289 |
| f ₅ | 265 | 330 | 415 | 480 |
| L, | 469.5 | 548.5 | 678 | 759 |
| I | 140 | 170 | 210 | 250 |
| I, | 137 | 156 | 196 | 220 |
| М | 195 | 235 | 280 | 360 |
| S | 250 | 290 | 335 | 435 |

We reserve the right to make dimensional and constructional alterations.

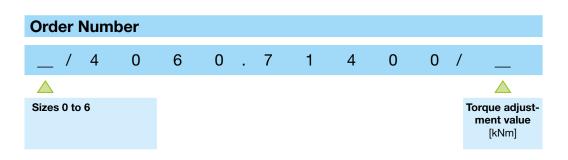


flange design

Type 4060.71400 Sizes 0 to 6







Example: Order number 5 / 4060.71400 / 200

| Technical data | | | | | | Size | | | |
|----------------------------|------------------|-------|----------|-----------|---------|-----------|----------|--------------|--------------|
| recrimical data | | | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| Limit torques for overload | M_{G} | [kNm] | 7.5 - 15 | 12.5 - 25 | 20 - 40 | 37.5 - 75 | 70 - 140 | 125 - 250 | 220 - 440 |
| Number of EAS®-elements | | | 6 | 8 | 6 | 8 | 12 | 10 | 10 |
| Sizes EAS®-elements | | | 0 | 0 | 1 | 1 | 1 | 2 | 2 |
| Maximum speed | n _{max} | [rpm] | 2000 | 1750 | 1500 | 1250 | 1000 | 900 | 750 |
| Bolt stroke on overload | | [mm] | 6 | 6 | 8 | 8 | 8 | 12 | 12 |

| Mass mamonto of inartic or | d wa | iahta | Sizes | | | | | | | | |
|------------------------------------|------|-------|-------|------|------|-------|-------|-------|------|--|--|
| Mass moments of inertia an | 0 | 1 | 2 | 3 | 4 | 5 | 6 | | | | |
| EAS®-element-side | 0.25 | 0.5 | 1.16 | 2.71 | 5.51 | 16.29 | 27.87 | | | | |
| EAS®-pressure flange side J [kgm²] | | | 0.19 | 0.37 | 0.96 | 2.05 | 4.22 | 10.29 | 19.3 | | |
| Weight at d _{max} | | [kg] | 56 | 77 | 142 | 212 | 303 | 627 | 814 | | |

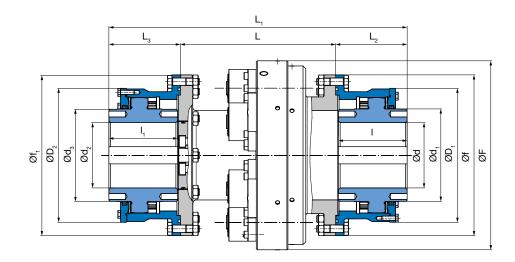
| Dimensions | | | | Sizes | | | |
|-----------------|-----|-----|-----|-------|-----|-----|-----|
| [mm] | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| b _{h7} | 175 | 230 | 255 | 310 | 340 | 460 | 540 |
| е | 214 | 269 | 306 | 360 | 400 | 531 | 618 |
| D | 234 | 292 | 330 | 390 | 430 | 567 | 660 |
| F | 275 | 320 | 380 | 455 | 545 | 620 | 720 |
| f | 3 | 3 | 4 | 4 | 5 | 6 | 6 |
| i | 11 | 13 | 13 | 17 | 17 | 21 | 25 |
| L | 226 | 243 | 298 | 312 | 328 | 476 | 485 |

We reserve the right to make dimensional and constructional alterations.

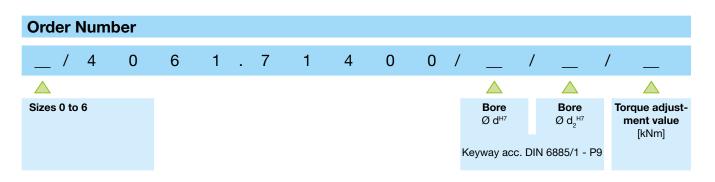


Toothed coupling

Type 4061.71400 Sizes 0 to 6







Example: Order number 4 / 4061.71400 / 180 / 200 / 90

| Technical Data | | | | | | | | Size | | | |
|--|--------------------------------------|---------|--------------------|-------|----------|-----------|---------|-----------|----------|--------------|--------------|
| recrimical Data | | | | | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| Limit torques for ov | verload | | M_{G} | [kNm] | 7.5 - 15 | 12.5 - 25 | 20 - 40 | 37.5 - 75 | 70 - 140 | 125 - 250 | 220 - 440 |
| Number of EAS®-ele | ments | | | | 6 | 8 | 6 | 8 | 12 | 10 | 10 |
| Sizes EAS®-elements | S | | | | 0 | 0 | 1 | 1 | 1 | 2 | 2 |
| Maximum speed | Maximum speed n _{max} [rpm] | | [rpm] | 2000 | 1750 | 1500 | 1250 | 1000 | 900 | 750 | |
| Bolt stroke on over | load | | | [mm] | 6 | 6 | 8 | 8 | 8 | 12 | 12 |
| Toothed coupling | Permitted | axial | ΔK_{a} | [mm] | ±2 | ±3 | ±3 | ±3 | ±3 | ±4 | ±4 |
| with crowned teeth | misalign- | radial | ΔK_r | [mm] | 7.5 | 8.6 | 10.2 | 11.7 | 12.4 | 18.4 | 20.6 |
| cutting ments $^{1/2)}$ angular ΔK_{w} | | [mm] | 1.25 | 1.25 | 1.25 | 1.25 | 1.25 | 1.25 | 1.25 | | |
| Nominal and maximum torques, T_{KN} [kNm] | | 12.5 | 25 | 40 | 63 | 100 | 250 | 400 | | | |
| toothed coupling w cutting | ith crowne | d teeth | T _{K max} | [kNm] | 25 | 50 | 80 | 12.6 | 200 | 500 | 800 |

¹⁾ The values refer to 1500 rpm. 2) Per joint

| Mass moments of inertia and weights | | Sizes | | | | | | | |
|--|---|--------|------|------|------|------|------|-------|-------|
| | | 0 | 1 | 2 | 3 | 4 | 5 | 6 | |
| EAS®-pressure flange side | J | [kgm²] | 0.27 | 0.65 | 1.48 | 3.33 | 6.43 | 19.17 | 39.74 |
| EAS®-element side | J | [kgm²] | 0.34 | 0.78 | 1.69 | 3.99 | 7.72 | 25.18 | 48.3 |
| Weight at d _{max} / d _{2max} | | [kg] | 83 | 132 | 220 | 345 | 488 | 1053 | 1523 |

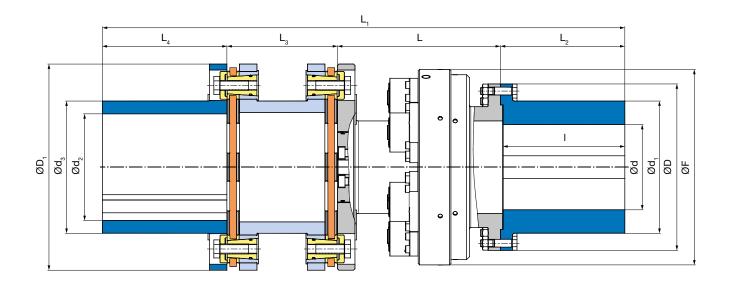
| Paras [mm] | | Sizes | | | | | | | | |
|---------------------------|--------------------|-------|-----|-----|-----|-----|-----|-----|--|--|
| Bores [mm] | 0 | 1 | 2 | 3 | 4 | 5 | 6 | | | |
| EAS®-pressure flange side | d _{max} | 95 | 130 | 150 | 185 | 210 | 285 | 340 | | |
| EAS®-element side | d _{2 max} | 95 | 130 | 150 | 185 | 210 | 285 | 340 | | |

| We reser | ve the right to make dimensional and | constructional |
|----------|--------------------------------------|----------------|
| | | alterations. |

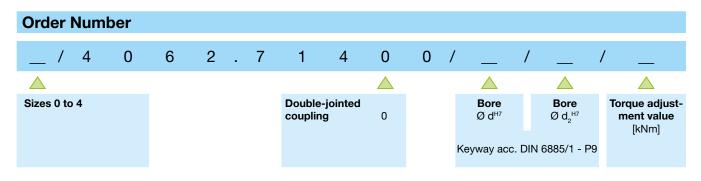
| Dimensions | | | | Sizes | | | |
|------------------------------|-----|-------|-----|-------|-----|------|------|
| [mm] | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| d ₁ | 135 | 185 | 210 | 255 | 290 | 400 | 480 |
| d ₃ | 135 | 185 | 210 | 255 | 290 | 400 | 480 |
| D ₁ | 195 | 251 | 288 | 337 | 375 | 502 | 584 |
| $D_{\!\scriptscriptstyle 2}$ | 195 | 251 | 288 | 337 | 375 | 502 | 584 |
| F | 275 | 320 | 380 | 455 | 545 | 620 | 720 |
| f | 234 | 292 | 330 | 390 | 430 | 567 | 660 |
| f ₁ | 234 | 292 | 330 | 390 | 430 | 567 | 660 |
| L | 226 | 242.5 | 298 | 312 | 328 | 476 | 485 |
| L, | 434 | 502.5 | 588 | 685 | 740 | 1012 | 1125 |
| L ₂ | 104 | 130 | 145 | 186.5 | 206 | 268 | 320 |
| L ₃ | 104 | 130 | 145 | 186.5 | 206 | 268 | 320 |
| I | 100 | 125 | 140 | 180 | 200 | 260 | 310 |
| l _t | 100 | 125 | 140 | 180 | 200 | 260 | 310 |

backlash-free

Type 4062.71400 Sizes 0 to 4







Example: Order number 4 / 4062.71400 / 180 / 200 / 90

| Tooknied Dat | | | | | | | Size | | |
|---|------------------|----------------|--------------------|----------|-----------|---------|-----------|----------|------|
| Technical Dat | lecililicai Data | | | | | 1 | 2 | 3 | 4 |
| Limit torques for overload | | M_{G} | [kNm] | 7.5 - 15 | 12.5 - 25 | 20 - 40 | 37.5 - 75 | 70 - 140 | |
| Number of EAS®-6 | elements | | | | 6 | 8 | 6 | 8 | 12 |
| Sizes EAS®-eleme | ents | | | | 0 | 0 | 1 | 1 | 1 |
| Maximum speed | | | n _{max} | [rpm] | 2000 | 1750 | 1500 | 1250 | 1000 |
| Bolt stroke on ov | erload | | | [mm] | 6 | 6 | 8 | 8 | 8 |
| T | Permitted | axial | ΔK_{a} | [mm] | 1.6 | 1.7 | 2.1 | 2.3 | 2.3 |
| Torsionally rigid shaft coupling | misalign- | radial | ΔK_r | [mm] | 1.0 | 1.0 | 1.1 | 1.3 | 1.4 |
| ments ¹⁾ angular ΔK | | ΔK_{w} | [°] | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | |
| Nominal and maximum torques, T_{KN} [kNm] | | 22 | 33 | 50 | 73 | 110 | | | |
| torsionally rigid a | all-steel cou | pling | T _{K max} | [kNm] | 44 | 66 | 100 | 146 | 220 |

¹⁾ The values refer to 1500 rpm.

| Mass moments of inertia and weights | | | | Sizes | | | | | | |
|-------------------------------------|------------------------|---|---------------------|-------|------|------|------|-------|--|--|
| | | | | 0 | 1 | 2 | 3 | 4 | | |
| Mass moments of | f Hub side | J | [kgm²] | 0.35 | 0.76 | 1.58 | 3.68 | 6.56 | | |
| inertia | torsionally rigid side | J | [kgm ²] | 0.86 | 1.73 | 3.5 | 7.1 | 13.95 | | |
| Weight at d _{max} | | | [kg] | 132 | 195 | 308 | 468 | 665 | | |

| Porce [mm] | | | | Sizes | | |
|------------------------|--------------------|-----|-----|-------|-----|-----|
| Bores [mm] | 0 | 1 | 2 | 3 | 4 | |
| Hub-side | d _{max} | 140 | 170 | 180 | 220 | 240 |
| Torsionally rigid side | d _{2 max} | 140 | 160 | 180 | 210 | 240 |

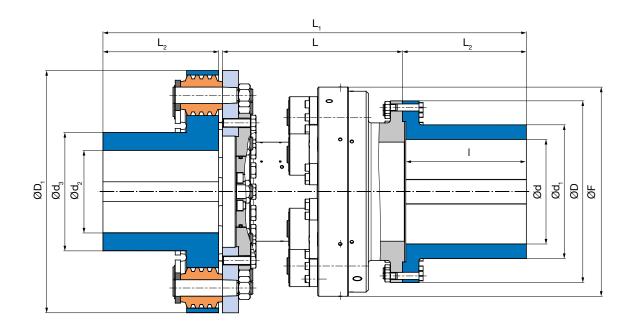
| Dimensions | | | Sizes | | |
|-------------------|-------|-------|-------|--------|------|
| [mm] | 0 | 1 | 2 | 3 | 4 |
| d ₁ | 186 | 230 | 243 | 300 | 321 |
| d_3 | 186 | 215 | 243 | 279 | 321 |
| D | 234 | 292 | 330 | 390 | 430 |
| D ₁ | 290 | 332 | 378 | 431 | 492 |
| F | 275 | 320 | 380 | 455 | 545 |
| L | 229 | 245.5 | 302 | 316 | 330 |
| L, | 735 | 811.5 | 934 | 1054.5 | 1173 |
| $L_{_2}$ | 175 | 200 | 225 | 265 | 310 |
| L ₃ | 155.6 | 166 | 182 | 208.4 | 223 |
| L ₄ | 175 | 200 | 225 | 265 | 310 |
| I I | 171 | 195 | 219 | 260 | 302 |

We reserve the right to make dimensional and constructional alterations.

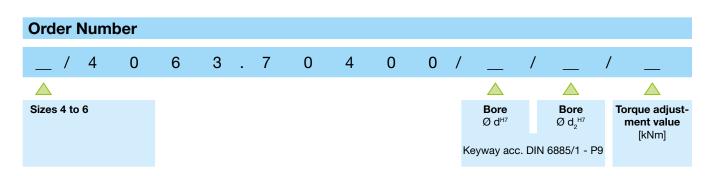
lastic bolt

Type 4063.70400

Sizes 4 to 6







Example: Order number 4 / 4063.70400 / 270 / 180 / 90

| Technical Da | 4~ | | | | | Sizes | |
|------------------------------|-----------|-----------------|--------------------|---------|------------|-----------|-----|
| lechnical Da | la | | | | 4 | 5 | 6 |
| Limit torques for overload | | M_{G} | [kNm] | 40 - 80 | 72.5 - 145 | 130 - 260 | |
| Number of EAS®- | elements | | | | 12 | 10 | 10 |
| Sizes EAS®-elem | ents | | | | 1 | 2 | 2 |
| Maximum speed | i | | n _{max} | [rpm] | 1000 | 900 | 750 |
| Bolt stroke on o | verload | | | [mm] | 8 | 12 | 12 |
| Florida. | Permitted | axial | ΔK_{a} | [mm] | ±4 | ±4 | ±4 |
| Flexible shaft coupling | misalign- | radial | ΔK_r | [mm] | 1.5 | 1.5 | 1.5 |
| ments 1) angular | | ΔK_{w} | [mm] | 4.6 | 5.3 | 6.4 | |
| Nominal and maximum torques, | | T _{KN} | [kNm] | 48 | 100 | 160 | |
| flexible coupling | l | | T _{K max} | [kNm] | 96 | 200 | 320 |

| Mass moments of inartia and weights | | | | Sizes | | | | | |
|-------------------------------------|---------------|---|---------------------|-------|-------|--------|--|--|--|
| Mass moments of inertia and weights | | | 4 | 5 | 6 | | | | |
| Mass moments | of Hub side | J | [kgm²] | 6.6 | 20.02 | 39.63 | | | |
| inertia | Flexible side | J | [kgm ²] | 22.35 | 55.18 | 110.68 | | | |
| Weight at d _{max} | | | [kg] | 706 | 1407 | 1956 | | | |

| Bores [mm] | | Size | | | | |
|---------------|--------------------|------|-----|-----|--|--|
| | | 4 | 5 | 6 | | |
| Hub-side | d _{max} | 240 | 300 | 340 | | |
| Flexible side | d _{2 max} | 225 | 250 | 320 | | |

| Dimensions | Sizes | | | | |
|------------------------------|-------|------|------|--|--|
| [mm] | 4 | 5 | 6 | | |
| d ₁ | 321 | 420 | 500 | | |
| d_3 | 320 | 360 | 450 | | |
| D | 430 | 567 | 660 | | |
| D ₁ | 660 | 760 | 920 | | |
| F | 545 | 620 | 720 | | |
| L | 375 | 533 | 543 | | |
| L, | 946 | 1201 | 1231 | | |
| $L_{\!\scriptscriptstyle 2}$ | 310 | 350 | 370 | | |
| $L_{\scriptscriptstyle{3}}$ | 250 | 300 | 300 | | |
| I | 302 | 342 | 362 | | |

We reserve the right to make dimensional and constructional alterations.

¹⁾ The values refer to 1500 rpm.



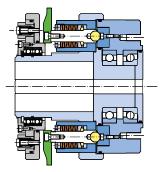
EAS®-HT Options

For the EAS®-HT clutches, designs specially created according to customer requests and different variants are also available.

EAS®-HT clutches can be combined with additional attachment parts.

We are happy to advise you on the dimensioning and configuration of your optimum design.

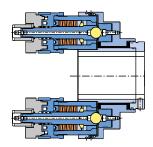
EAS®-HT with automatic re-engagement



After overload occurrence, the EAS®-HT torque limiter is disengaged. It is possible to engage the EAS®-HT torque limiter via remote control by means of automatic re-engagement. Re-engagement can be carried out pneumatically, hydraulically, electromechanically or mechanically.



EAS®-HT with mechanical disengagement

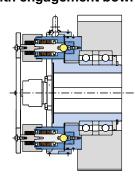


Mechanical disengagement device for the EAS®-elements.

The EAS $^{\otimes}$ -elements can be disengaged individually mechanically.



EAS®-HT with engagement bowl

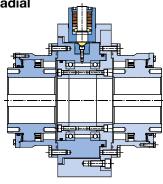


Engagement without aids.

Automatic engagement device for low operating speeds. Direct overload query possible through switching disk.



EAS®-HT radial



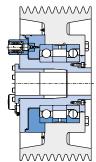
EAS®-HT radial for small construction space length values and low to medium operating speed values.





EAS®-HT Options

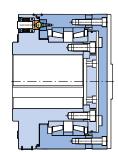
EAS®-HT with integrated drive elements



EAS®-HT, integrated attachment of sprocket and toothed wheels, V-belt disks etc.



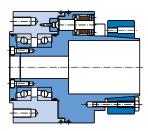
EAS®-HT for roller gears



Highest torques at lowest diameters. The alternative to hydraulic clamping sets and shear pins in rolling mills.



Frictionally-locking shaft-hub connection



Frictionally-locking shaft-hub connections:

- Shrink disk (see Fig.)
- External shrink disk hub
- Oil press fit

EAS®-HT low temperature design



Reliable overload protection in case of very low temperatures to -48 °C.

(Please contact the manufacturer separately for this).



ATEX design



EAS®-HT torque limiters are also available in ATEX design according to the directive 94/9 EC (ATEX 95).

(Please contact the manufacturer separately for this).



EAS®-element

Application

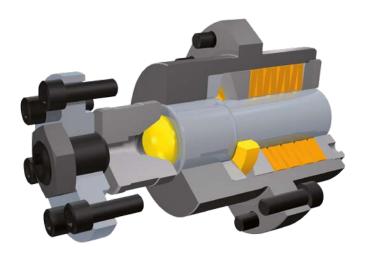
- □ EAS®-elements for installation in two bearingsupported flanges facing each other or for integration into existing constructions
- ☐ As EAS®-HT torque limiter component
- ☐ For customer-specific constructions

Applications

- □ Conveyor belts
- □ Crushers
- ☐ Rolling mills
- ☐ Underground mining / mining
- □ Raw material extraction

Advantages/Benefits

- ☐ Safe overload protection
- ☐ Can be used flexibly and in modular form
- ☐ Maximum performance density
- ☐ Release forces adjustable
- ☐ Easy and quick engagement
- ☐ Large number of disengagement procedures
- ☐ Re-greasing via the cone lubricating nipple





Rustproof design available on request

Function:

Positive locking transmission of circumferential force and axial force. In case of overload, the EAS®-elements separate the input and output mechanically, so that the system can slow down freely. Manual re-engagement of the individual elements (automatic reengagement available on request).



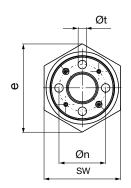
The catalogue contains basic information on pre-selection and dimensioning.

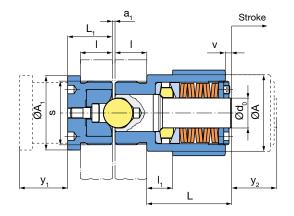
For detailed information on selection, dimensioning, installation, initial operation and maintenance, please see the Installation and Operational Instructions.



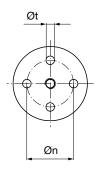
EAS®-element

Standard

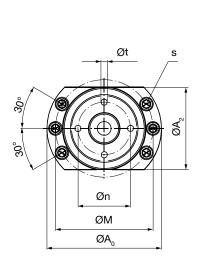


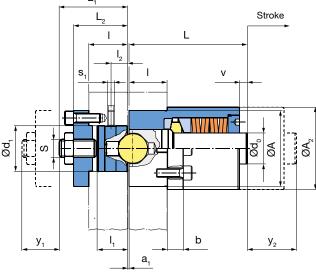


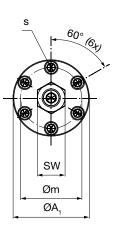
Type 440._04.0 Sizes 02 to 01



Type 440._04.0 Sizes 0 to 2

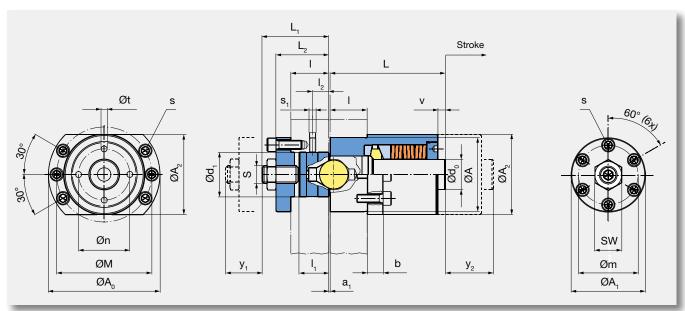






Reinforced

Type 441.604.0 Sizes 0 to 2



EAS®-element

| Technical Data | | | | Sizes | | | | |
|-------------------|---------------------------------------|---------------------|------|-------|------|------|------|------|
| | | | 02 | 01 | 0 | 1 | 2 | |
| | Type 440.404.0 (Low torque range) | F _{u min} | [kN] | 0.22 | 1 | 1.8 | 5 | 4 |
| | | F _{u max} | [kN] | 0.54 | 2 | 5 | 10 | 11 |
| | Type 440.504.0 | F _{u min} | [kN] | 0.5 | 1.25 | 3.75 | 7.5 | 10 |
| Circumferential | (Medium torque range) | F _{u max} | [kN] | 1.4 | 2.5 | 7.5 | 15 | 30 |
| force | Type 440.604.0 | F _{u min} | [kN] | 1.2 | 2.5 | 7.5 | 15 | 30 |
| | (High torque range) | F _{u max} | [kN] | 2.5 | 5 | 15 | 30 | 60 |
| | Type 441.604.0 Reinforced design | F _{u min} | [kN] | - | - | 19 | 38 | 75 |
| | | F _{u max} | [kN] | - | - | 38 | 75 | 150 |
| | Type 440.404.0 (Low torque range) | F _{ax min} | [kN] | 0.2 | 0.9 | 1.62 | 4.5 | 3.6 |
| | | F _{ax max} | [kN] | 0.48 | 1.8 | 4.5 | 9 | 9.9 |
| | Type 440.504.0 (Medium torque range) | F _{ax min} | [kN] | 0.45 | 1.12 | 3.37 | 6.75 | 9 |
| Axial force | | F _{ax max} | [kN] | 1.26 | 2.25 | 6.75 | 13.5 | 27 |
| | Type 440.604.0 (High torque range) | F _{ax min} | [kN] | 1.08 | 2.25 | 6.75 | 13.5 | 27 |
| | | F _{ax max} | [kN] | 2.25 | 4.5 | 13.5 | 27 | 54 |
| | Type 441.604.0 Reinforced design | F _{ax min} | [kN] | - | - | 10 | 20 | 40 |
| | | F _{ax max} | [kN] | - | - | 20 | 40 | 80 |
| Bolt stroke on ov | erload | [mm] 2.5 4 6 | | | 6 | 8 | 12 | |
| Weights | | | [kg] | 0.25 | 0.6 | 1.75 | 4.1 | 11.3 |

| Dimensions | | | Sizes | | |
|----------------------|------|------|-------|-----|------|
| [mm] | 02 | 01 | 0 | 1 | 2 |
| A H8 | 28 | 38 | 55 | 75 | 100 |
| A _o | - | - | 85 | 110 | 150 |
| A ₁ | 28 | 35 | 55 | 75 | 100 |
| $\mathbf{A}_{_{2}}$ | - | - | 55 | 75 | 108 |
| a ₁ | 1.0 | 1.5 | 2 | 2 | 3 |
| b | - | - | 12 | 15 | 20 |
| d _o | 10 | 14 | 20 | 30 | 40.6 |
| d _{1 h7} H8 | - | - | 30 | 40 | 60 |
| е | 31.2 | 41.6 | - | - | - |
| L | 28 | 40 | 73 | 96 | 160 |
| L, | 15 | 21 | 52 | 65 | 80 |
| L ₂ | - | - | 42 | 51 | 70 |
| I | 12 | 15 | 30 | 40 | 50 |

| Dimensions | | | Sizes | | |
|-------------------------------------|----------|-----------------------|------------------|------------------|-------------------|
| [mm] | 02 | 01 | 0 | 1 | 2 |
| I, | 7 | 10 | 22 | 30 | 40 |
| l ₂ | - | - | 12 | 17 | 22 |
| М | - | - | 72 | 95 | 128 |
| m | - | - | 44 | 60 | 80 |
| n | 17 | 22 | 31 | 48 | 69 |
| S | - | - | M12 | M20 | M24 |
| s | M24x1 1) | M30x1,5 ²⁾ | M6 ³⁾ | M8 ⁴⁾ | M12 ⁵⁾ |
| S ₁ | - | - | M5 | M6 | M8 |
| sw | 27 | 36 | 19 | 30 | 36 |
| t | 3 | 4 | 5 | 6 | 8 |
| v | 2 | 3 | 3 | 4 | 15 |
| У ₁ ⁶⁾ | 12 | 15 | 8 | 10 | 10 |
| y ₂ ⁶⁾ | 16 | 21 | 38 | 50 | 65 |

We reserve the right to make dimensional and constructional alterations.

EAS®-element Standard

Order Number

4 . 0 0 / 4 4 0. Sizes Torque range 4 5 02 low 01 medium 0 high 6 1

Example: Order number 0 / 440.504.0

- 1) Tightening torque $M_A = 40 \text{ Nm}$ 2) Tightening torque $M_A = 60 \text{ Nm}$
- 3) Fixing screw DIN EN ISO 4762 10.9 $M_{\Delta} = 9 \text{ Nm}$

EAS®-element Reinforced

Order Number

1.6 0 4.0 / 4

Sizes

0 1

2

Example: Order number 0 / 441.604.0

- 4) Fixing screw DIN EN ISO 4762 10.9 $\rm M_A$ = 19 Nm 5) Fixing screw DIN EN ISO 4762 10.9 $\rm MM_A$ = 76 Nm
- 6) y_1 and y_2 are extension dimensions

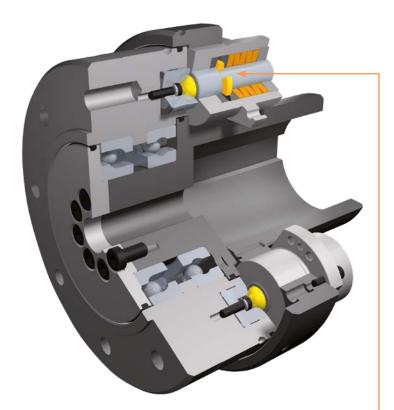


Characteristics

- □ Positive locking torque transmission acc. to the ball-detent principle
- ☐ Adjustable torque
- □ Separates disengagingly
- ☐ Easy repeat operation start-up
- □ Robust
- □ Long service lifetime



Rustproof design available on request



Design

All clutch parts are made of steel. EAS®-HT torque limiters basic components have a zinc-phosphated surface which provides a basic corrosion protection for further surface treatments.

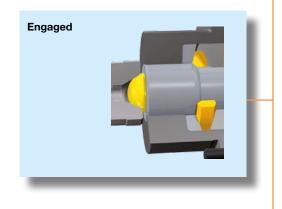
Clutch types 4050, 4060 are also suitable for oil running.

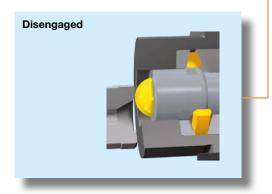
The limit torque for overload on the clutch can be adjusted by changing the cup spring pre-tension of each overload element.

The EAS®-HT torque limiters can be set to the required limit torque for overload at the place of manufacture. Subsequent torque changes can be carried out using the Adjustment Diagram included in the delivery (see respective Installation and Operational Instructions).

Operating principle of the EAS®-HT torque limiter Overload elements

- ☐ If the proportional circumferential force on the individual elements proves too large, the resulting axial force causes an axial movement of the bolt via the ball/calotte system and therefore the disconnection of the torque transmission.
- ☐ The maximum circumferential force is individually determined through the adjusting nut and *mayr*®-cup springs. The transmittable torque is determined in this way.
- Due to the axial stroke of the bolt (ball carrier), the control segments move radially outwards, thereby disconnecting the components axially.
- ☐ Re-engagement of the balls through a bolt stroke in the direction of the calotte takes place either manually or via a *mayr*® re-engagement device (pneumatic, hydraulic, electromechanical or mechanical).







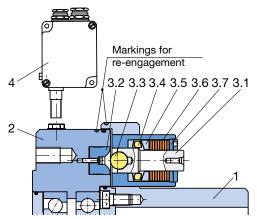
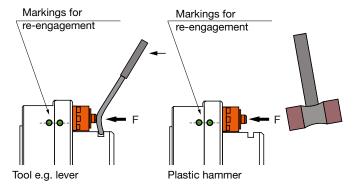


Fig. 2: EAS®-HT torque limiter disengaged state

Processes for torque switch-off on overload:

On overload, the hub part 1 and the output flange 2 begin to turn against each other. The bolts 3.1 in the overload elements are pressed via the control segments 3.4 against the force of the cup springs 3.6 from the thrust pieces 3.2. The control segments 3.4 travel radially outwards over the bolt 3.1 switching edge and hold the bolts 3.1 in a disengaged position (see Fig. 2). The positive locking connection of the hub part 1 and the output flange 2 is nullified. The originally coupled masses can slow down freely. The drive is switched off electrically via speed monitoring device 4.



Re-engagement:

Turn the hub part 1 and the output flange 2 into the correct angular position to one another (re-engagement position can be recognized via the marking bores on the clutch outer diameter, Fig. 3). By applying axial pressure on the bolt end, bolts 3.1 are brought back to their engaged position. The clutch is ready for operation when all clutch overload elements are engaged.

Fig. 3

Maintenance

The EAS®-HT torque limiters do not require special maintenance work. They are largely protected against dust and humidity, they have an initial grease filling and are therefore mainly maintenance-free.

EAS®-elements Please find a detailed description in the respective Installation and Operational Instructions (go to www.mayr.com). Special maintenance work may be necessary, however, if the device is subject to large amounts of dirt or dust or is operating in extreme ambient conditions.

In this case, please contact the manufacturer.

Mounting onto the shaft:

In a standard delivery, the EAS®-HT torque limiters are delivered with a finish bore and a keyway acc. DIN 6885/1 P9. The clutch can be secured axially onto the shaft e.g. using a washer and a screw, screwed into the shaft threaded centre hole.

Optionally, we deliver a frictionally-locking shaft-hub connection (see EAS®-HT options, page 19).

Pre-selection of the clutch

Drive lines in heavy engineering are robust and designed for operation in adverse conditions. In contrast to systems with servomotor-driven drives, the torque course and the system behaviour often cannot be determined precisely.

Frequently, only the drive power of the motor and the permitted max. torque of the gear output are known.

Using tried-and-tested operating factors, clutch sizes suitable for the application can be pre-selected.

Pre-selection

$$T_{N} = \frac{9550 \times P}{n}$$
 [Nm]

$$T_{G} \approx T_{N} \times K_{B}$$
 [Nm]

| Names | Names: | | | | |
|----------------|--------|--|--|--|--|
| T _N | [Nm] | Nominal torque of the motor | | | |
| $T_{\rm G}$ | [Nm] | Pre-selected release torque on the overload clutch | | | |
| Р | [KW] | Input power motor | | | |
| n | [rpm] | Speed | | | |
| K _B | [-] | Service factor | | | |

| Service | Service factors: | | | | | |
|---------|-------------------|--|--|--|--|--|
| 2.5 - 3 | medium impacts | Stirring units / pumps (viscid fluids) / kneading machines / mixing systems / conveyor belts / etc. | | | | |
| 3 - 5 | high impacts | Shredding machines / centrifuges / crushers / roll trains / construction machines / mining machines / etc. | | | | |

In normal operation, the EAS®-HT transmits the set overload torque via positive locking. All torques for normal operation, including torque peaks, must be transmitted safely and must not cause the torque limiter to respond.

Often, the actual complex of loads (impacts) during operation (e.g. for shredding machines / mixers) are not known and can only be measured in the system with great effort.

Using software specially developed for the purpose, it is possible to simulate the behaviour in case of collisions of such drive lines. The prerequisite is that all specifications are known:

- Mass moments of inertia
- ☐ Rigidities of all overload elements, including the overload clutch
- ☐ Parameters of the motor and the control circuit



Particularly in case of load-side vibration generation (e.g. piston compressors / shredding machines / etc.) or alternating torques **please contact us** to select a reliable, tried and tested overload protection for your production systems.

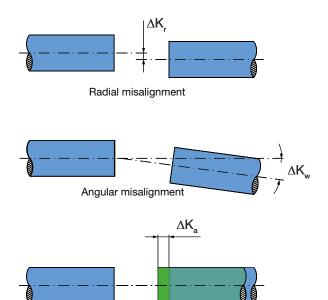
Here, the overload clutch is combined with suitable couplings, depending on the application:

- □ Elastomer coupling
- □ Disk pack coupling
- ☐ Toothed coupling

Profit from our many years of market and application experience in different branches.



Misalignment compensation capability of the different shaft misalignment compensation couplings



Axial displacement

Fig. 4

Shaft Misalignment

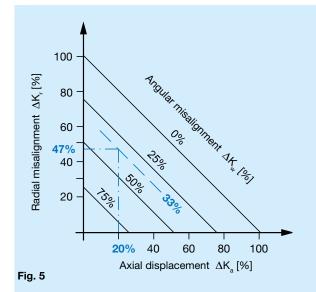
Misalignments between shafts occur due to manufacturing and assembly tolerances, bearing backlash and temperature influences.

This can cause axial, radial and angular shaft misalignment.

The shaft misalignment compensation couplings of the EAS®-HT torque limiters can compensate for misalignments.

The misalignment possibilities of the shaft misalignment compensation coupling are general guideline values (see table "Technical Data").

In the application, the aim is to produce as precise a shaft alignment as possible, so that the bearing loads are reduced to a minimum.



If more than one kind of misalignment takes place simultaneously, they influence each other. The permitted misalignment values are dependent on one another. The sum total of the actual misalignments – in percent of the maximum value – must not exceed 100 %.

Example:

EAS®-HT lastic, Size 8 Type 4053.00400.0

- □ Axial displacement occurrence: $\Delta K_a = 0.5$ mm; equals 20 % of the permitted maximum value $\Delta K_a = 2.5$ mm
- ☐ Angular misalignment occurrence: $\Delta K_w = 0.1$ mm, equals 33 % of the permitted maximum value $\Delta K_w = 0.3$ mm
- ☐ Radial misalignment occurrence: $\Delta K_w = 0.14$ mm, equals 47 % of the permitted maximum value $\Delta K_w = 0.3$ mm



Product Summary

Torque Limiters/Overload Clutches

■ EAS®-Compact®/EAS®-NC/EAS®-smartic®

Positive locking and completely backlash-free torque limiting clutches

EAS®-reverse

Reversing, re-engaging torque limiter

■ EAS®-element clutch/EAS®-elements

Load-disconnecting protection against high torques

■ EAS®-axial

Exact limitation of tensile and compressive forces

EAS®-Sp/EAS®-Sm/EAS®-Zr

Load-disconnecting torque limiting clutches with switching function

ROBA®-slip hub

Load-holding, frictionally locked torque limiting clutches

ROBA®-contitorque

Magnetic continuous slip clutches

EAS®-HSC/EAS®-HSE

High-speed safety clutches for high-speed applications

shaft couplings

smartflex®/primeflex®

Perfect precision couplings for servo and stepping motors

■ ROBA®-ES

Backlash-free and damping for vibration-sensitive drives

ROBA®-DS/ROBA®-D

Backlash-free, torsionally rigid all-steel couplings

■ ROBA®-DSM

Cost-effective torque-measuring couplings



Electromagnetic Brakes/Clutches

ROBA-stop® standard

Multifunctional all-round safety brakes

ROBA-stop®-M motor brakes

Robust, cost-effective motor brakes

ROBA-stop®-S

Water-proof, robust monoblock brakes

ROBA®-duplostop®/ROBA®-twinstop®/ROBA-stop®-silenzio®

Doubly safe elevator brakes

ROBA®-diskstop®

Compact, very quiet disk brakes

ROBA®-topstop®

Brake systems for gravity loaded axes

■ ROBA®-linearstop

Backlash-free brake systems for linear motor axes

ROBA®-guidestop

Backlash-free holding brake for profield rail guides

□ ROBATIC®/ROBA®-quick/ROBA®-takt

Electromagnetic clutches and brakes, clutch brake units



■ tendo®-PM

Permanent magnet-excited DC motors











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